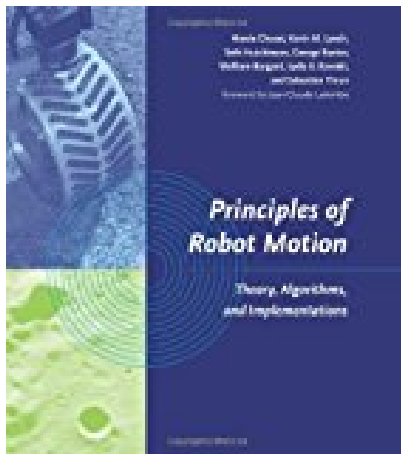


# Principles of Robot Motion Theory Algorithms and Implementations Intelligent Robotics and Autonomous Agents series

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